

GLOBAL Success partner.

Deployment Ceph Cluster Object Storage(RGW) using Rook Operator

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Why Object Storages?

Why do we need object storage?

- Cafe24 has been operating public cloud services based on openstack from 4Q 2020.
 - 2020: rocky version base, manually ceph nautilus rbd backend
 - 2022: xena version base
- For integrate various openstack components
 - Backup Service : Freezer
 - Database Service : Trove
- For various components that maintain the public cloud
 - Monitoring Metric/Logging (non gnocchi)
 - Kubernetes Storages
- For flexible infrastructure configuration, object service, not file service, has its strengths.
 - Using Loadbalancer(Octavia)
 - Lightweight static web site

Why Object Storages?

Needed a new deployment method based on our existing Ceph Cluster operation experience.

- Do stay up to date(at least with versions) [1]
 - Code Base Deployment/Upgrade
 - Dev/Staging/Prod ENV Ceph cluster
 - For testing parameters
 - Container Base Ceph Cluster
 - To solve OS dependency and version issues

How to deploy ceph?

Various deployment ceph cluster

Ceph-volume (manually)

• Simply, But It cannot be distributed consistently.

Ceph-deploy

- Very Simply, But It cannot be distributed consistently.
- These days ceph-deploy is no longer maintained, however, and doesn't even work with some newer distros like RHEL/CentOS 8.[1]
- Last Commit Oct 2, 2020(https://github.com/ceph/ceph-deploy)

· Ceph-ansible

- distributed consistently using ansible-playbook
- Non-Container/Container-based deployment is possible. (playbook yaml; like a code)

CephADM

- Container-based deployment.
- It doesn't offer a variety of components yet. (iSCSI gw,nfs ...)[1]

Rook Operator

- Deploy Ceph Cluster using Rook Operator
- CRD Base
- Very active project management
- There is a disadvantage of having to run kubernets for the operator.

What is Rook?

What is Rook?

- Makes storage available inside your Kubernetes cluster
- Self-managing, self-scaling, self-healing storage services[1]
- Automates the tasks of a storage administrator: deployment, bootstrapping, configuration, provisioning, scaling, upgrading, migration, disaster recovery, monitoring, and resource management.[1]
- Kubernetes Operators and Custom Resource Definitions
 - Block Pool CRD, Cluster CRD, Object Store CRD, Object Bucket Claim ...
- Automated management
 - Deployment, configuration, upgrades
- Open Source (Apache 2.0)
- 111 releases in 5 years

Storage Providers

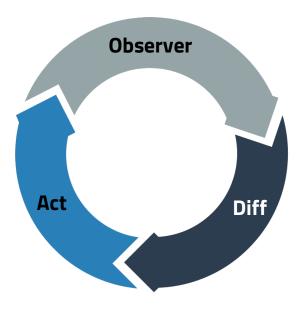
- Stable
 - Ceph
- Alpha
 - Cassandra
 - NFS



Rook Operator

Rook Operator

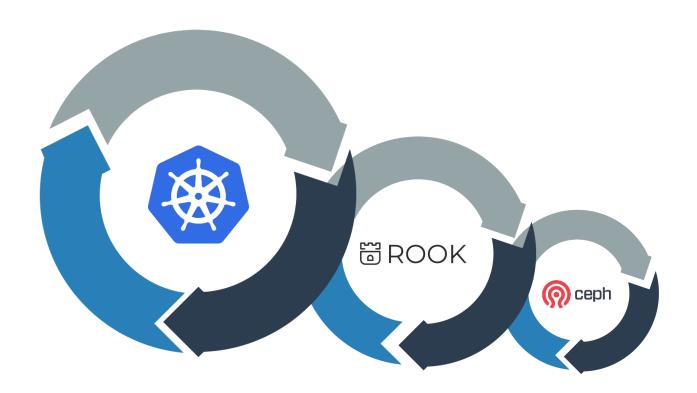
- It provides a more complicated reconciliation loop than the standard reconciliation loop of Kubernetes. So you can deploy and manage sensitive applications.
- So, in rook, ceph is deployed/managed through operator.
- The Rook operator automates configuration of storage components and monitors the cluster to ensure the storage remains available and healthy.[1]



Rook Operator

Rook Operator

- Reconciliation loop occurs logically, and while maintaining the Ceph cluster, Rook Operator replaces human intervention and proceeds with deployment/management.
- Management by logically connecting multiple reclamation loops.



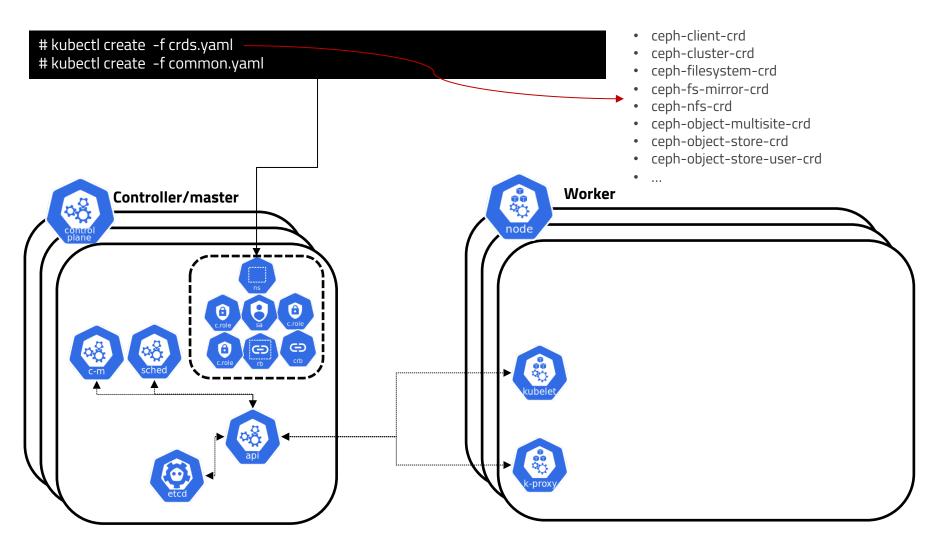
[1] https://www.slideshare.net/chrismceniry/evolving-for-kubernetes

Installation Rook(ceph)

- · simple deployment
 - CRD(CustomResourceDefinitions) deployment
 - # kubectl create -f crds.yaml
 - Namespace, RBAC deployment
 - # kubectl create -f common.yaml
 - Oerpator Config-Map, pod deployment
 - # kubectl create -f operator.yaml
 - Ceph Config-Map(;ceph.conf) deployment
 - # kubectl create -f rook-config-override.yaml
 - Ceph cluster deployment
 - # kubectl create -f cluster.yaml

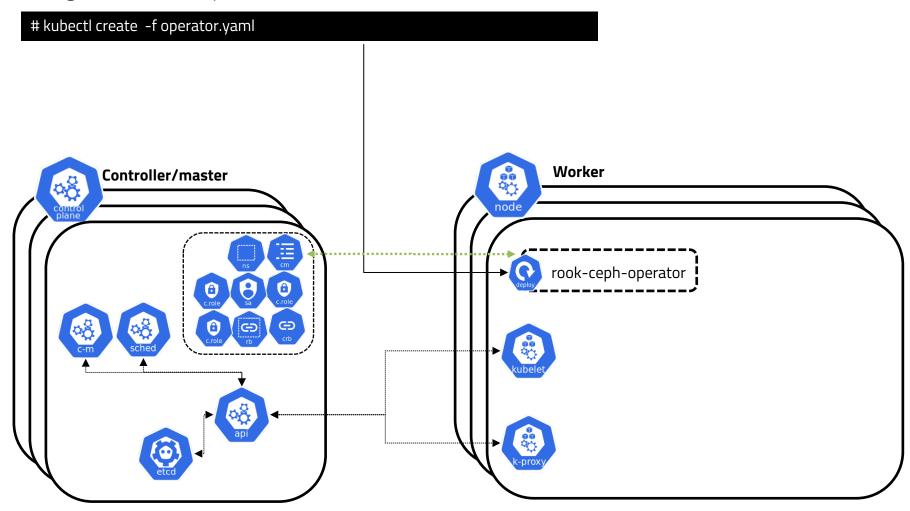
Installation Rook(ceph)

• Deploy ns, rbac and crd with common.yaml, crds.yaml for rook-ceph-operator configuration



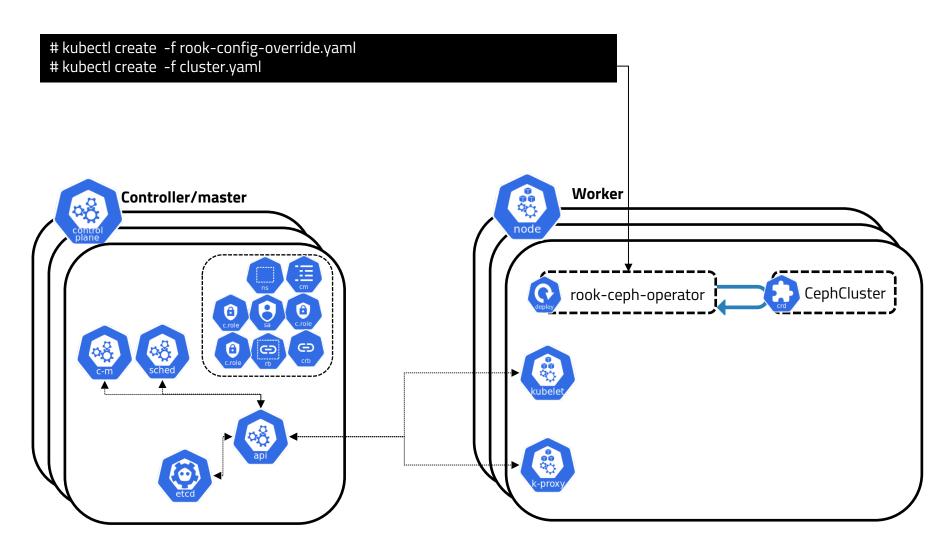
Installation Rook(ceph)

- Deploy configmap with operaator.yaml and operator and their settings
- Stating reconciliation loop



Installation Rook(ceph)

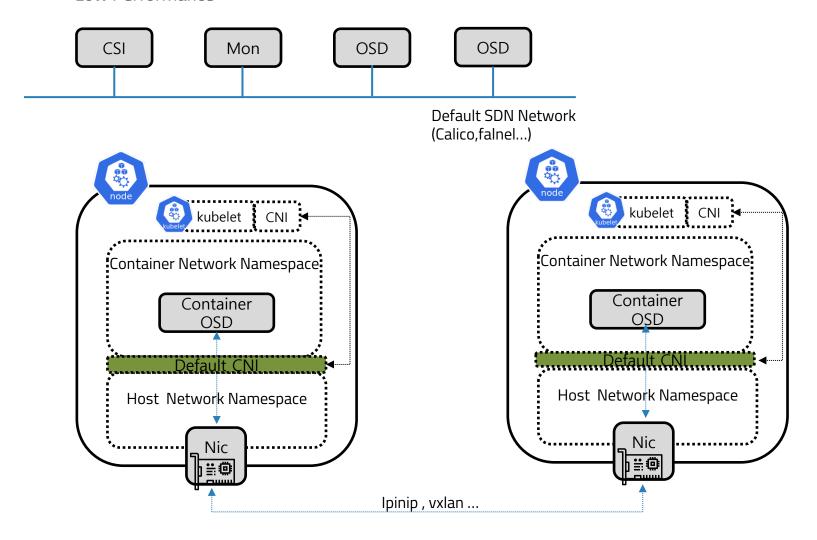
• Deploy rook-config-override cm to be used as ceph.conf and apply it to CephCluster CRD through cluster.yaml



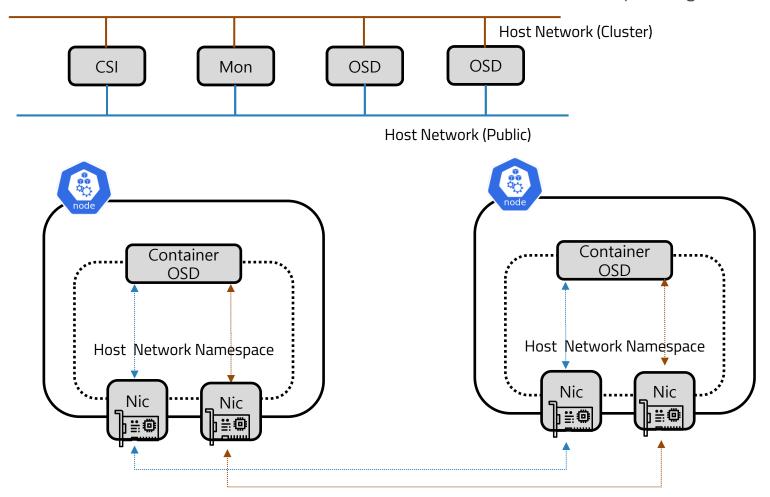
Installation Rook(ceph)

Ceph cluster deployment apiVersion: ceph.rook.io/v1 kind: CephCluster metadata: name: rook-ceph # kubectl create -f cluster.yaml namespace: rook-ceph spec: cephVersion: Ceph Version (image tag) image: quav.io/ceph/ceph:v16.2.6 dataDirHostPath: /var/lib/rook mon: Ceph Mon Setting count: 3 allowMultiplePerNode: false mgr: Ceph MGR Setting count: 1 modules: - name: pg_autoscaler enabled: true crashCollector: disable: false storage: useAllNodes: false useAllDevices: false nodes: Ceph OSD Setting - name: node-a devices: - name: "sdb" - name: node-b devices: - name: "sdb" - name: node-c devices: - name: "sdb" network: Ceph Network Setting provider: host #provider: multus

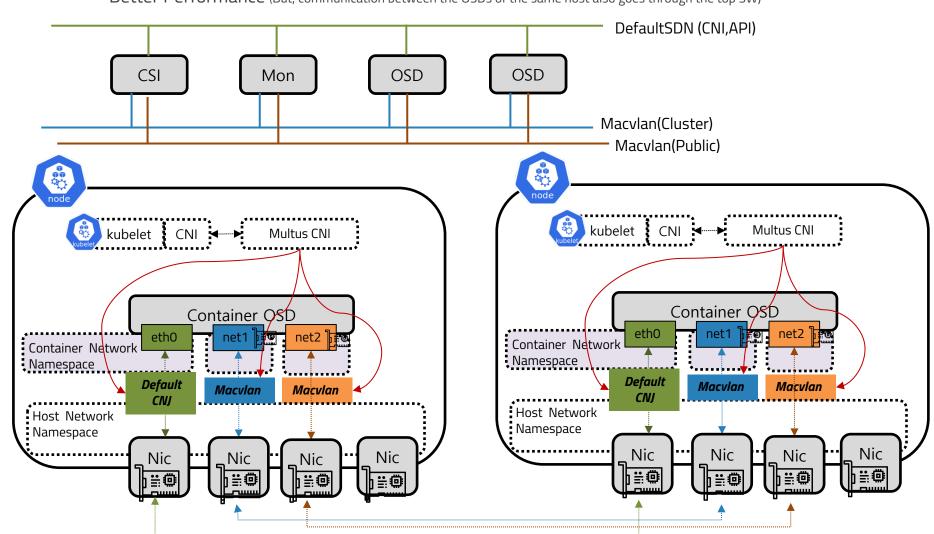
- Traditional pod networking single network interface default SDN
 - Security
 - Low Performance



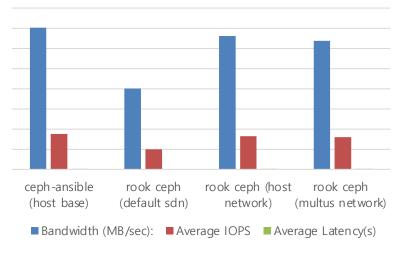
- Host networking runs on host network namespace and uses host IP. All host's network stack is visible
 - Better Performance than Default SDN(CNI)
 - Low Security
 - Unable to define client access (Defualt monitor access ; Kubernetes node ip binding)



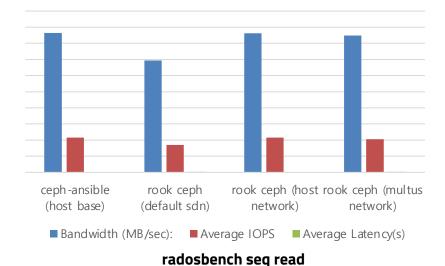
- Multus networking Rook supports addition of public and cluster network for Ceph
 - Security
 - Better Performance (But, communication between the OSDs of the same host also goes through the top SW)



- Comparison of network performance according to network type and deployment method
 - Default SDN: calico vxlan crosssubnet
 - All the same hardware setup

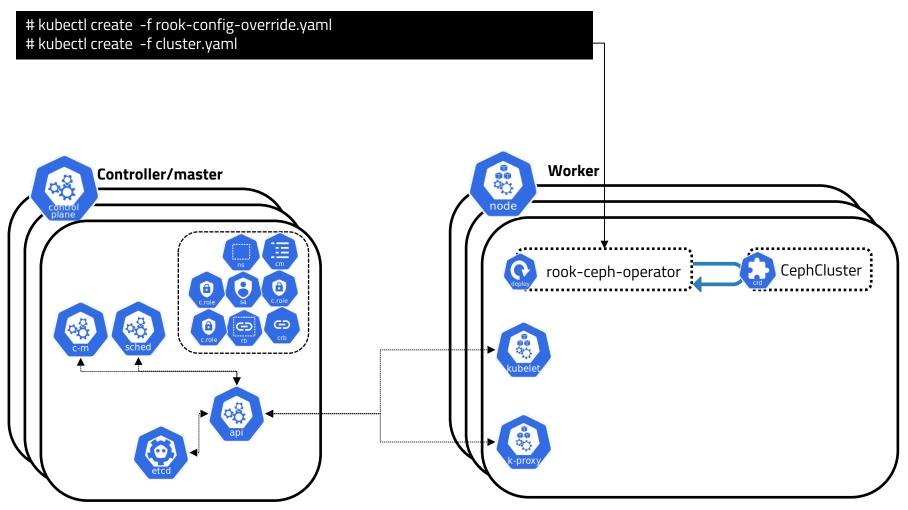


radosbench write



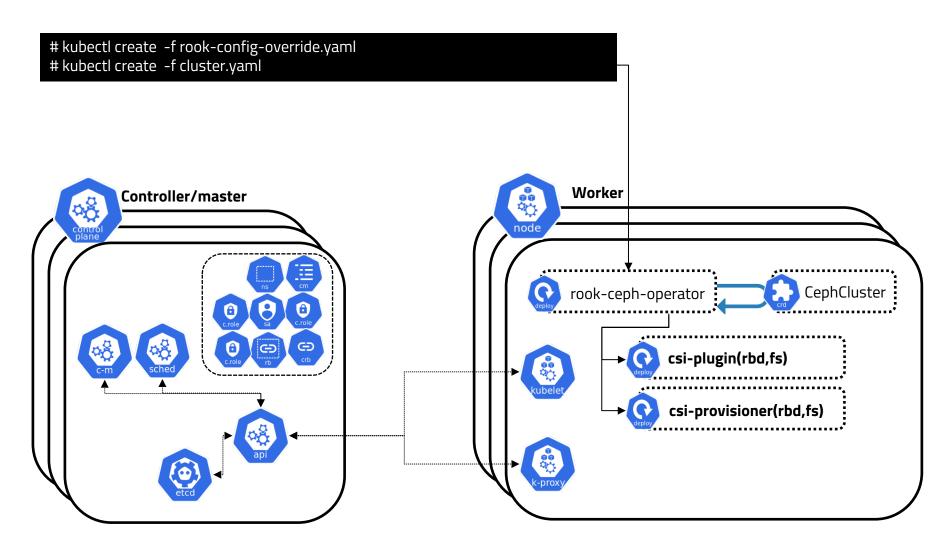
Installation Rook(ceph)

• Deploying of look-config-override cm to be used as ceph.conf and deploying of ceph clusters by applying it as a CephClusterkind through cluster.yaml.



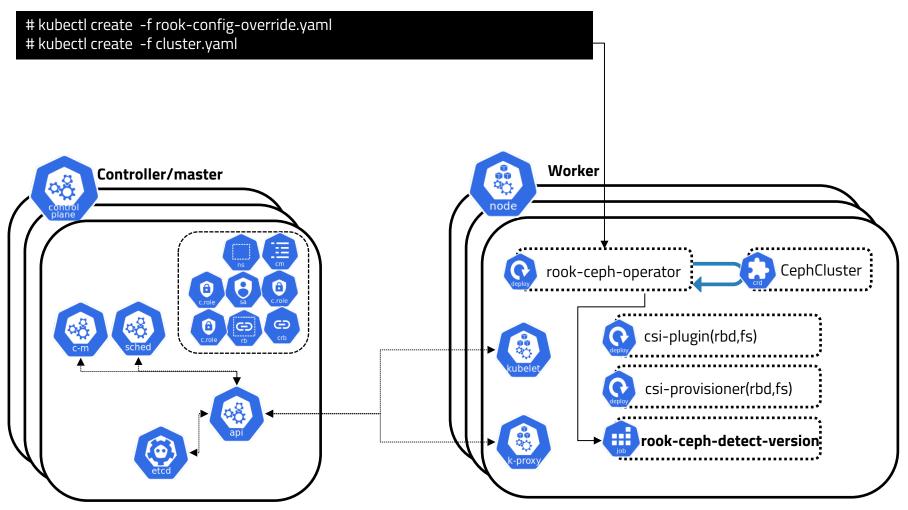
Installation Rook(ceph)

• Deploy csi(container storage interface) plugin,provisoner



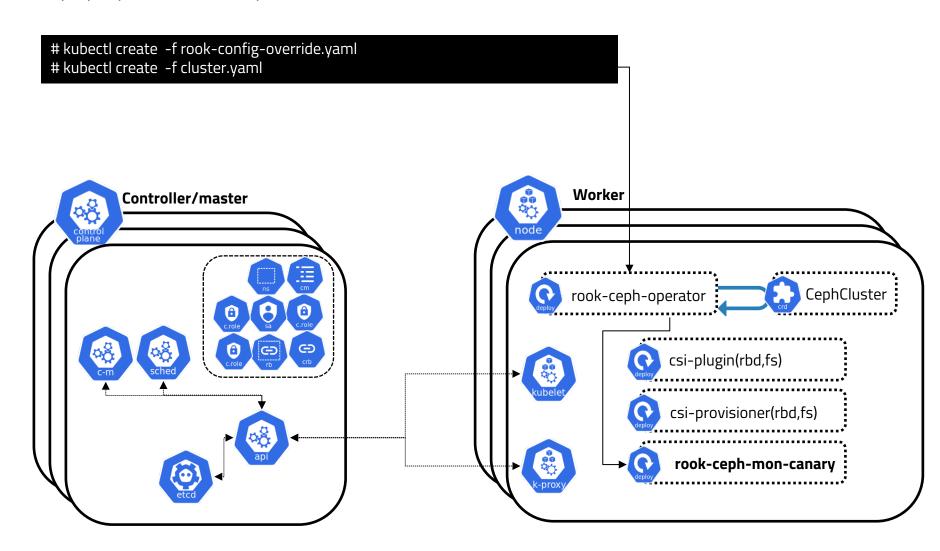
Installation Rook(ceph)

• The Rook Ceph operator creates a Job called rook-ceph-detect-version to detect the full Ceph version used by the given cephVersion.image



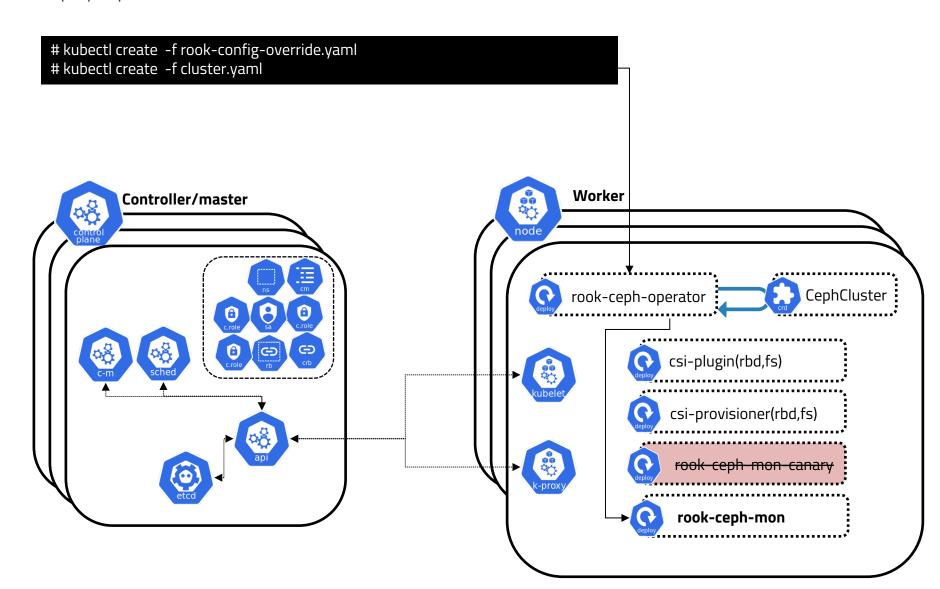
Installation Ceph Monitor

• Deploy Ceph Monitor Canary Pod



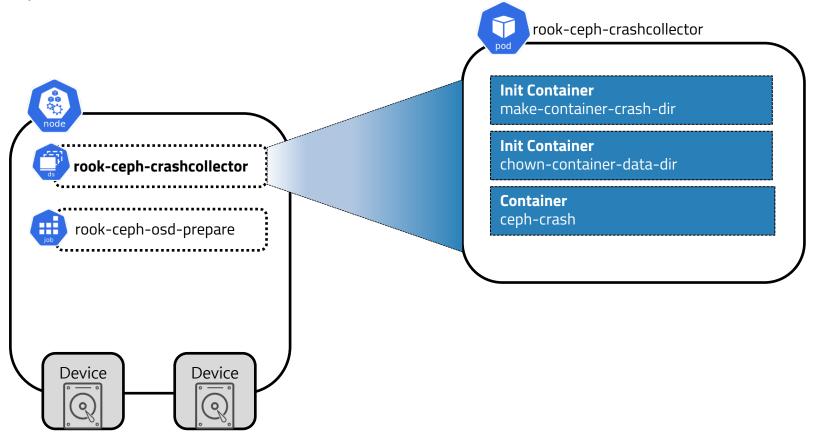
Installation Ceph Monitor

• Deploy Ceph Monitor Pod



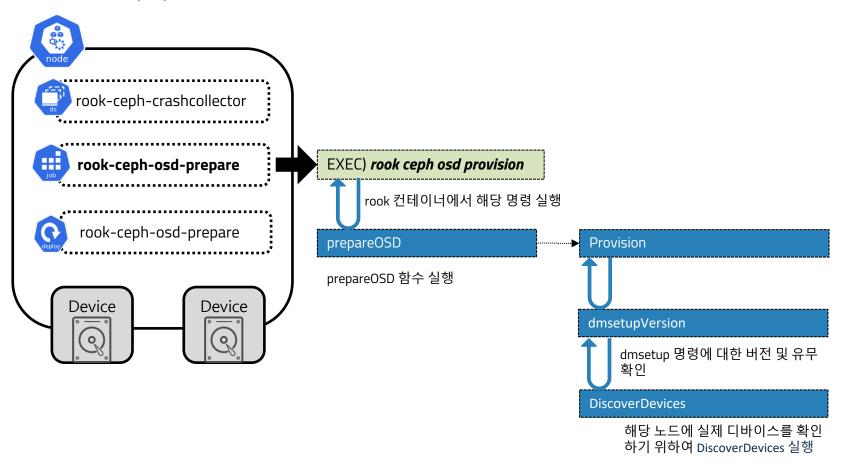
Crashcollector?

- Various system crash logs occurring in osd or mon can be checked by checking the crash log, but in the case of a container, it cannot be collected because it is terminated before the crash occurs.
- System crash logs of containers generated from all nodes with daemonset can be checked in pod and managed integrally.



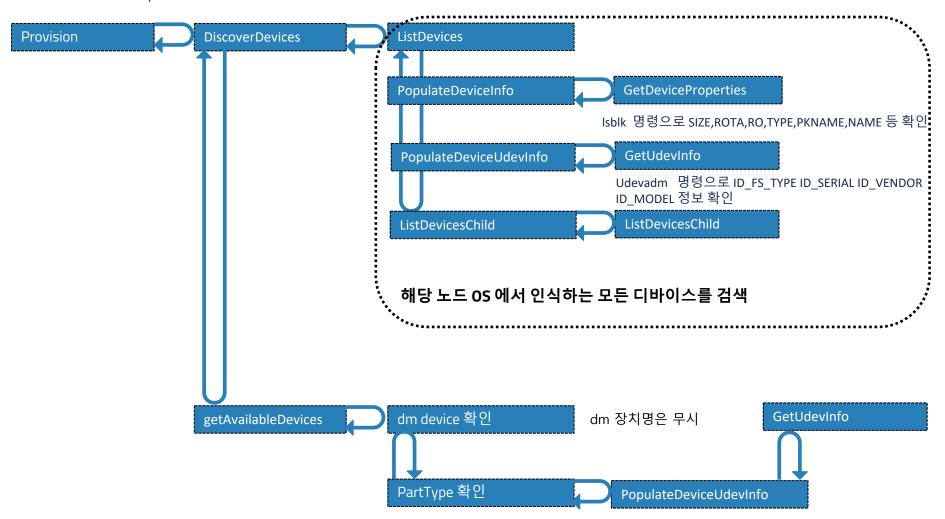
Prepare OSD

- Prepare process for executing osd by performing a look-ceph-osd-prepare job.
- Perform the rook cephosd provision command in pod.
- Execute the prepareOSD function.



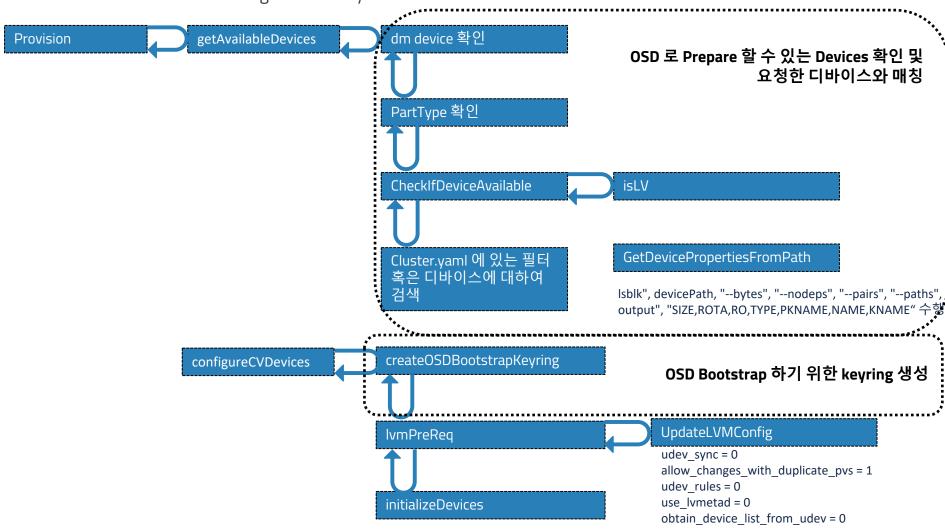
Prepare OSD

• Get all the actual physical device information of the node to be distributed and obtain information except for unnecessary devices.



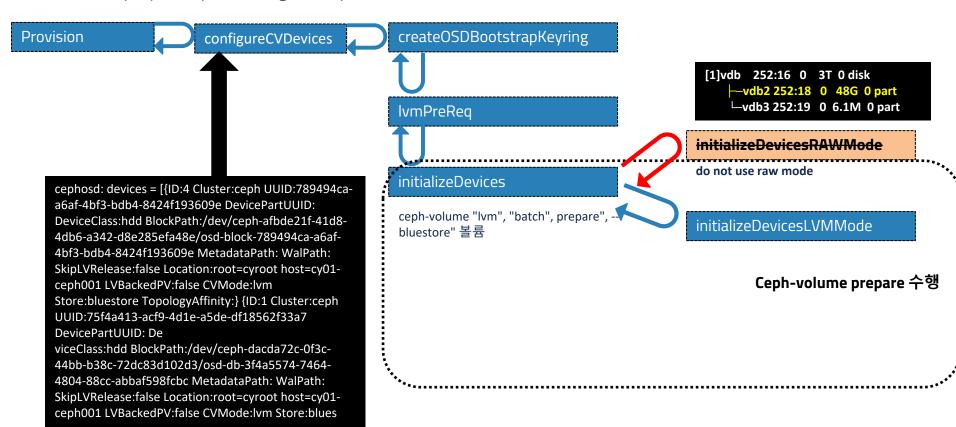
Prepare OSD

• Check information between the desired device and the actual physical device and proceed with deployment validation. Check the settings and binary file for Lvm.



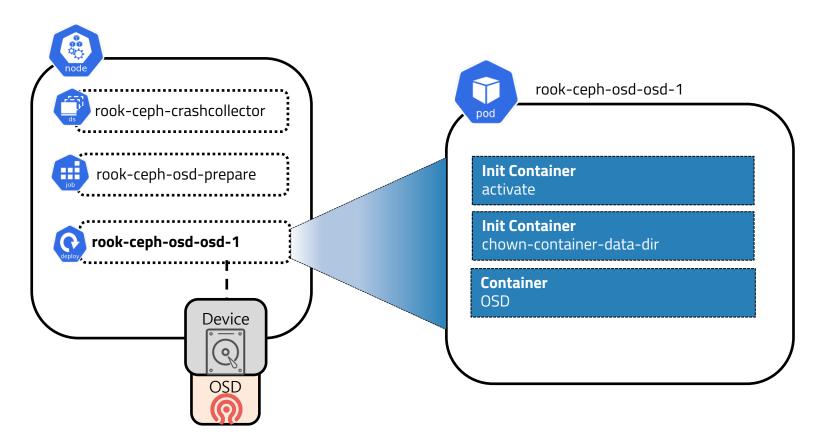
Prepare OSD

- Raw mode is currently unavailable due to issue [1] and is prepared to lvm mode by default.
- Proceed prepare by executing the ceph-volume command



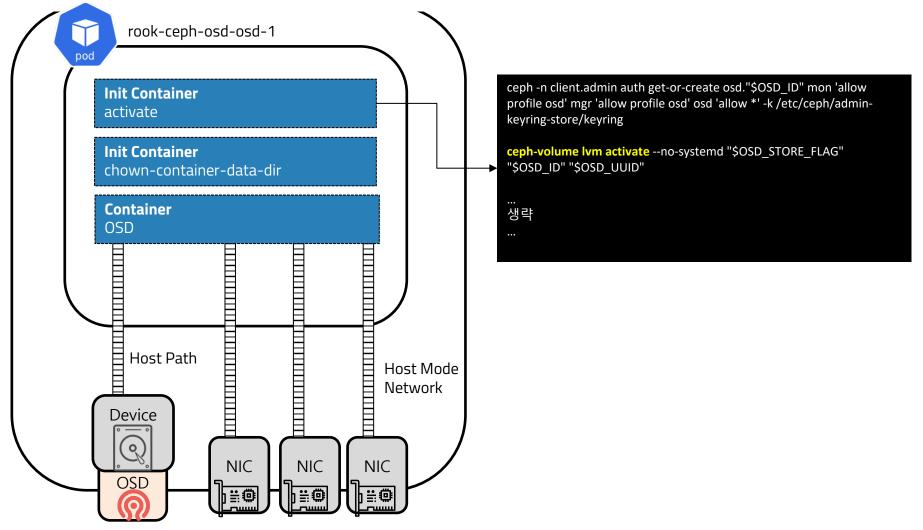
Run OSD Pod

• OSD Pod is separated into init container and cord container, and OSD operates normally only when the init process is performed normally.



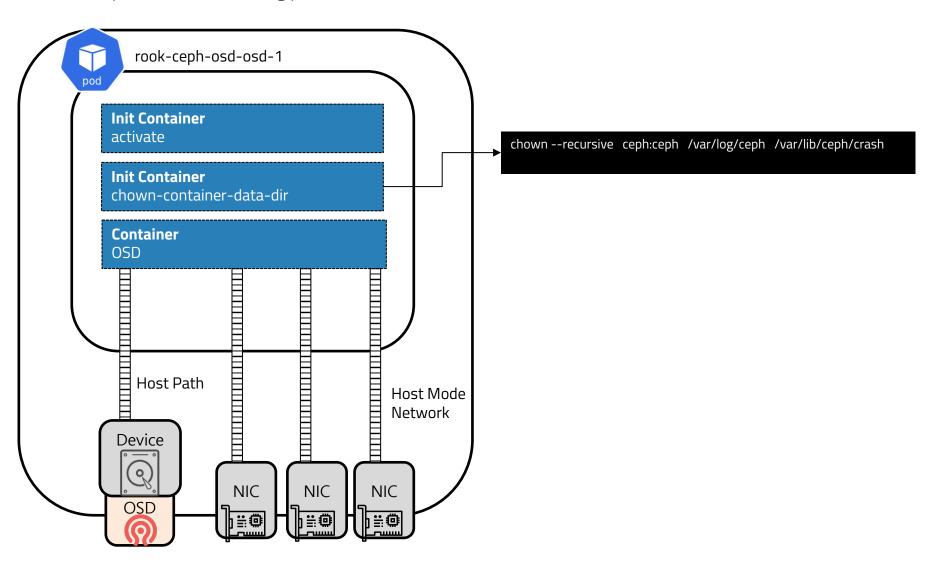
Run OSD Pod

• In active container, it plays a role in activating OSDs that have been prepare completed or previously terminated.



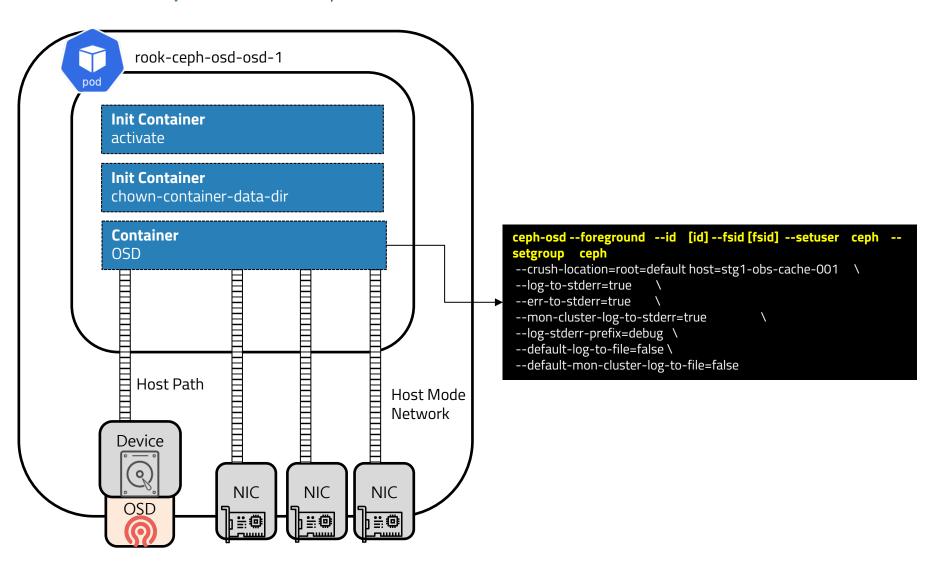
Run OSD Pod

• It sets permissions to the log path that Crashcollector will collect.



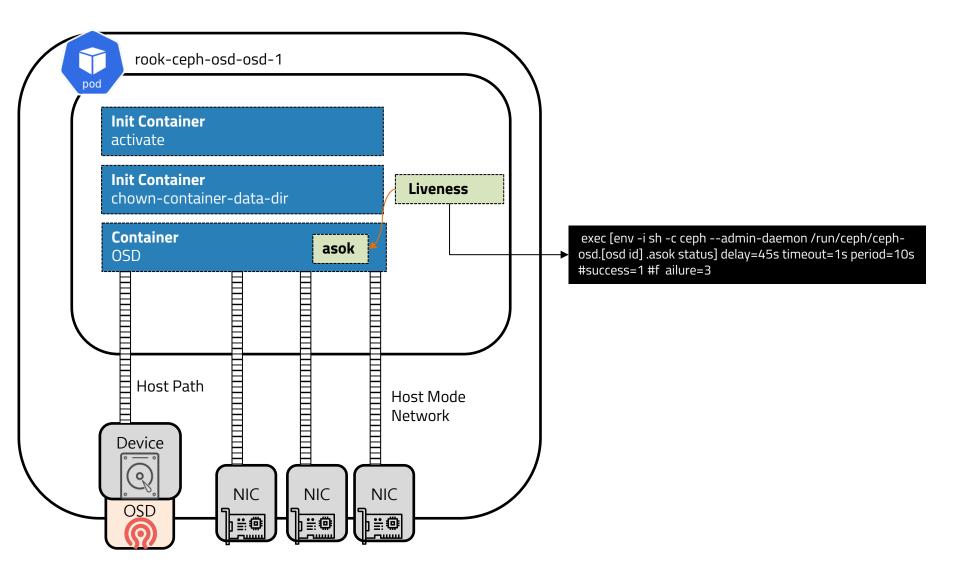
Run OSD Pod

• Execute the **ceph-osd** command by the osd container.



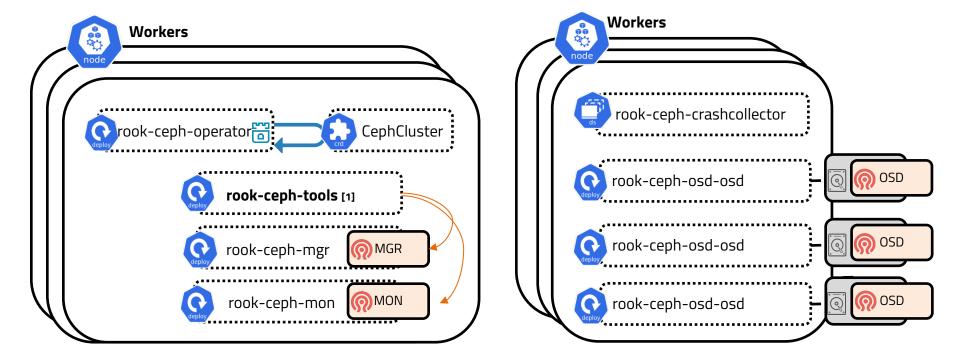
Run OSD Pod

Check Osd socket file and check liveness

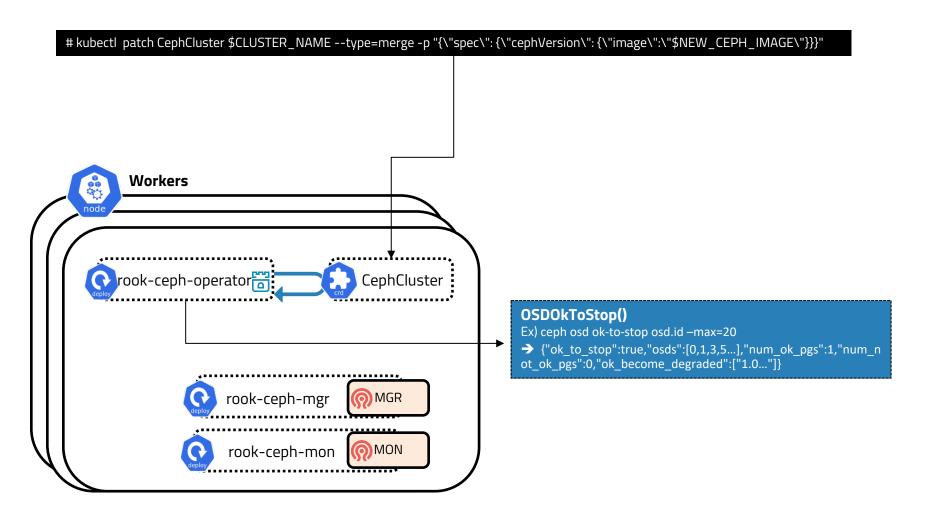


How to connect a client to Ceph Cluster

- Connect directly from host by installing Ceph client binary
 - A network connected to the monitor on the client node is required.
- Use rook-ceph-tools pod [1]
 - A network connected to the monitor in the client node is not required.
- Use kubectl-rook-ceph (https://github.com/rook/kubectl-rook-ceph)
 - By using the Krew plugin, only the ceph command is still provided, under development



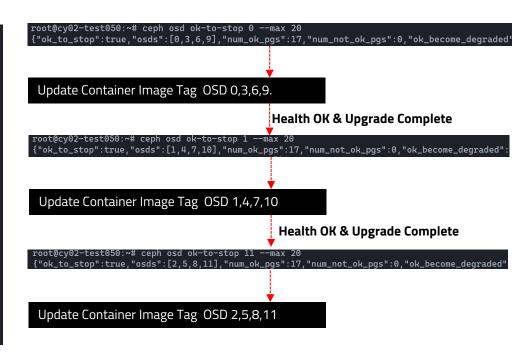
- Easily upgrade CephCluster by pod with changing Ceph image tag of CephCluster
- Execute **ceph osd ok-to-stop** command to proceed with the upgrade while replacing the pod container images sequentially so that the impact does no



How to upgrade rook ceph

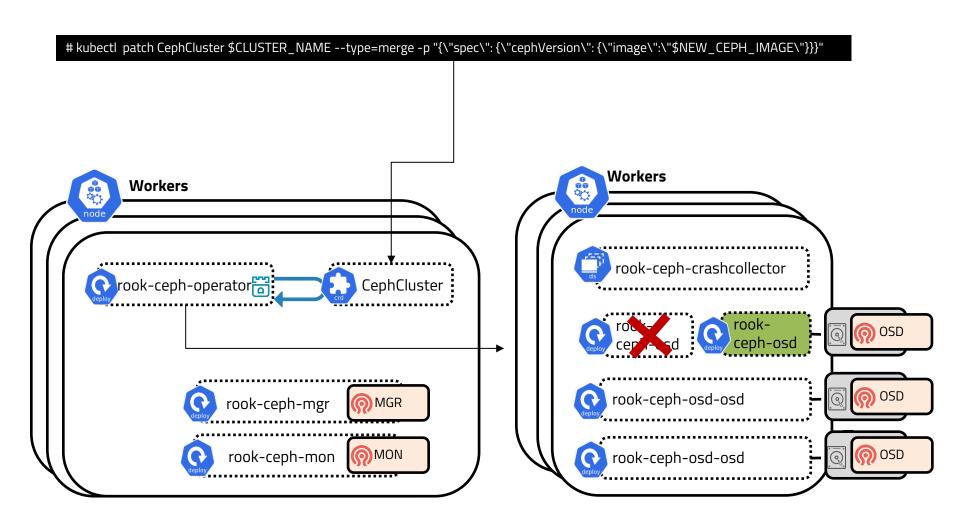
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```
root default
room room-1
    rack rack-1-1
        host cy01-ceph001
             osd.0
            osd.3
            osd.6
            osd.9
    rack rack-1-2
        host cy01-ceph002
            osd.1
            osd.4
            osd.7
            osd.10
    rack rack-1-3
        host cy01-ceph003
             osd.2
            osd.5
            osd.8
             osd.11
```



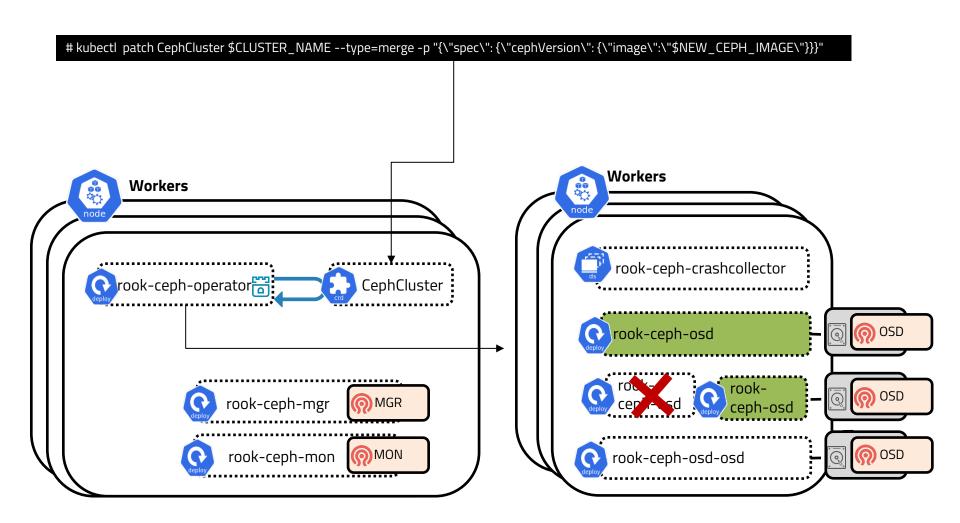
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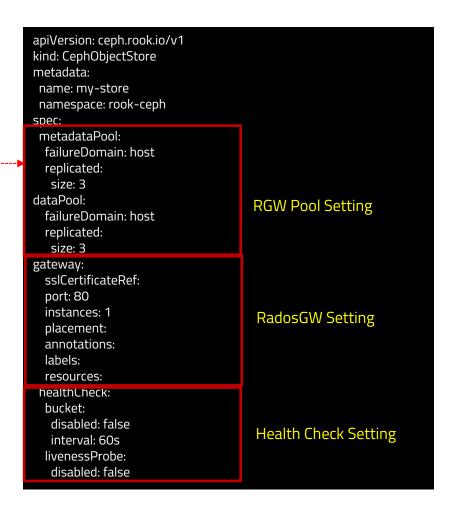


How to deploy Object Store

Rook Ceph Object Store (Ceph RGW)

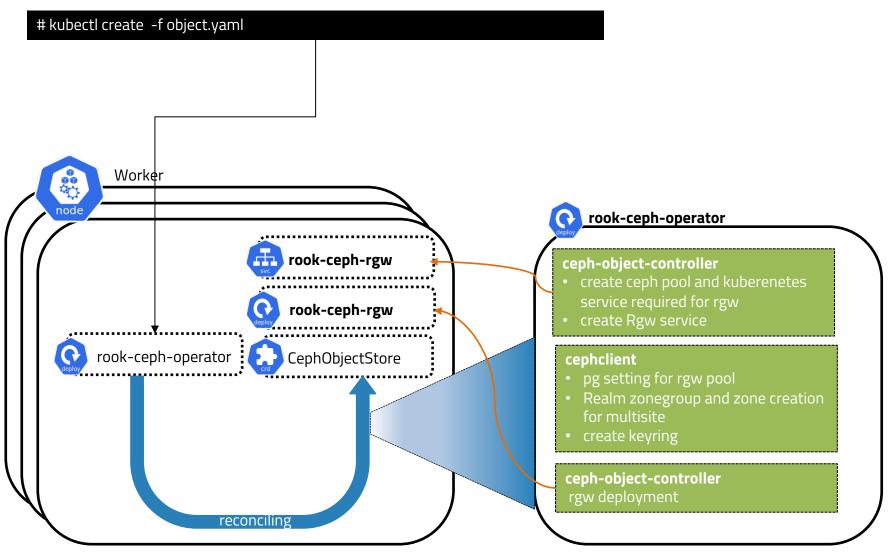
- Deploy Ceph Object Store through CRD
 - CephObjectStore: Ceph Object Store CRD
 - CephObjectRealm: Ceph Object Realm CRD
 - CephObjectZoneGroup: Ceph Object Zone Group CRD
 - CephObjectZone: Ceph Object Zone CRD
 - · ObjectBucketClaim: Ceph Object Bucket Claim
 - CephObjectStoreUser: Ceph Object Store User CRD

kubectl create -f object.yaml



How to deploy Object Store

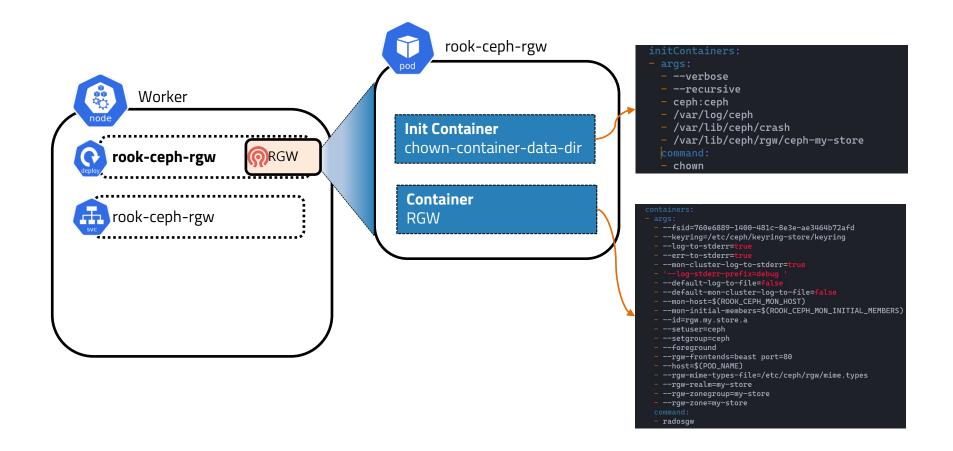
- To create a radosgw pod in the operator, use the ceph client to create pool, realm, zone, zonegroup
- Deploy rgw pod when the initialization process is completed



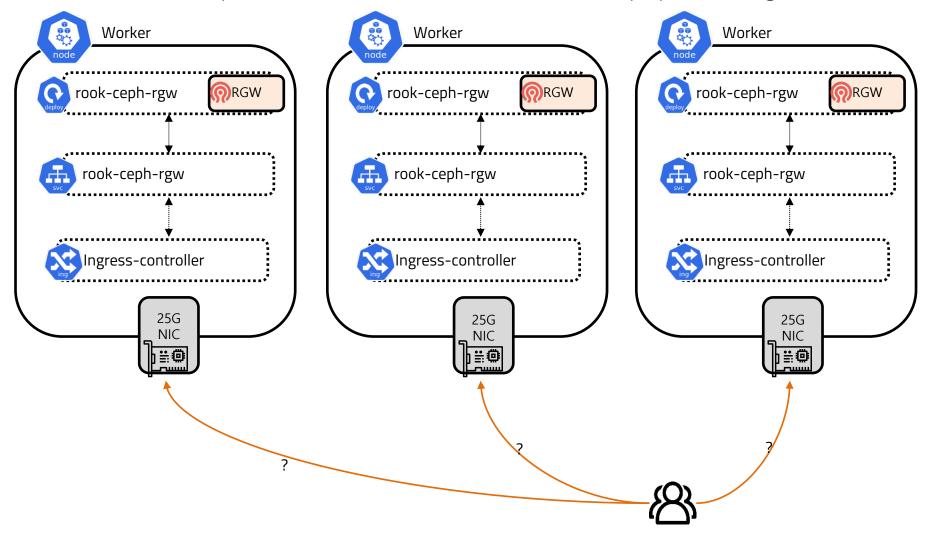
How to deploy Object Store

Rook Ceph Object Store (Ceph RGW)

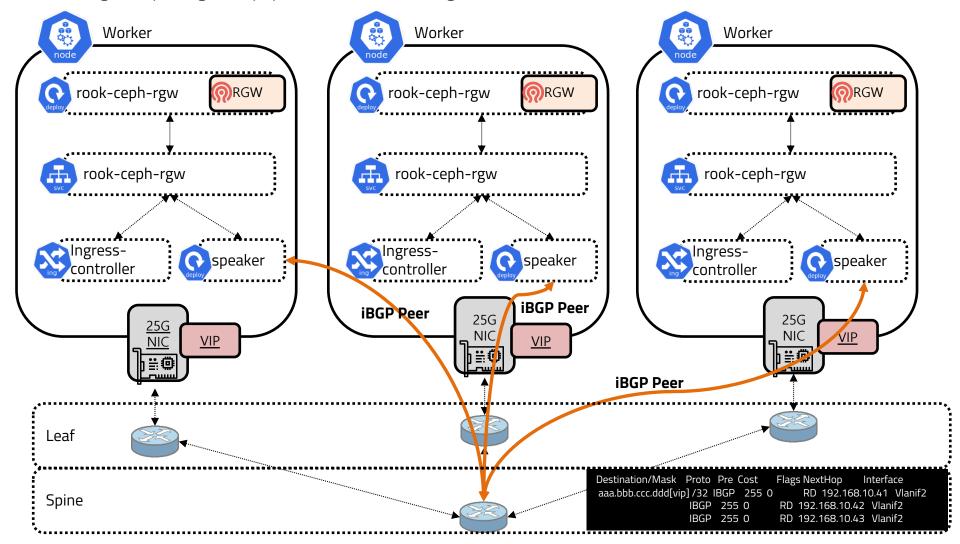
• After completion of Init Container Create an rgw pod using the radosgw command



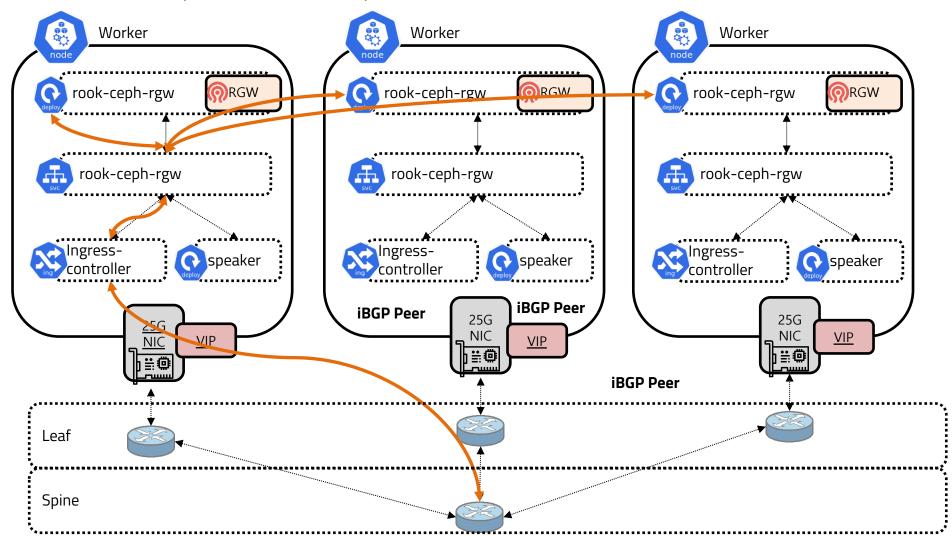
- Place rgw pods on 3 nodes to do a lot of processing
- For external exposure, nginx ingress controller was used.
- However, an lb, ecmp switch that distributes traffic to three nodes is very expensive. (using 25G nic...)



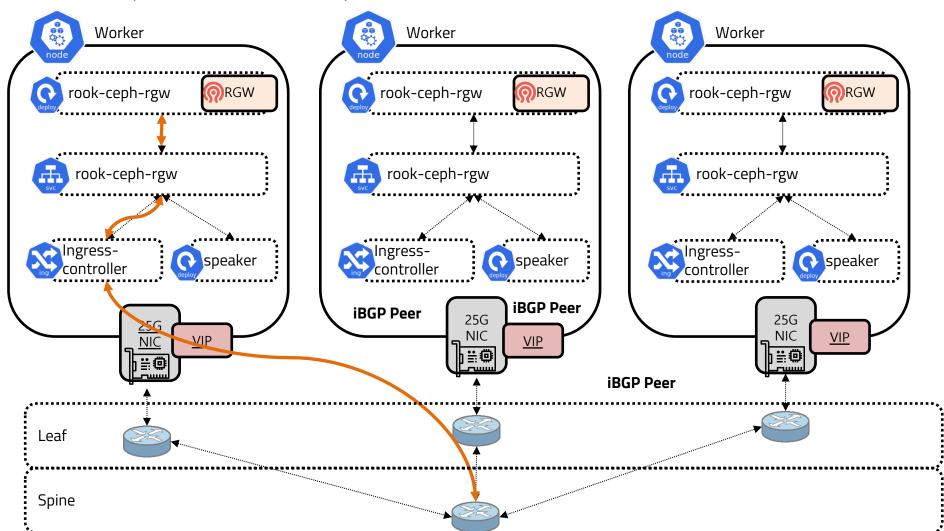
- Traffic is distributed from spine to multipath using metallb bgp mode
- A metallb speaker is deployed on the rgw node to become an ibpg peer with the spine.
- Configure vip assigned by speaker as service of ingress controller



- However, the traffic coming in from the outside is distributed, but once again in the rgw service.
 - Unnecessary traffic between nodes occurs
 - Unable to preserve client source ip address



- because the service's **externalTrafficPolicy** option is **cluster** by default.
 - By changing the **externalTrafficPolicy from cluster to host**, you can remove unnecessary traffic and preserve the client source ip



마지막으로

생각할점

- osd_memory_target 옵션은 고민해서 넣을것
- S3cmd to s5cmd
- 생각보다 많은 벤더의 참여로 빠른 버그 픽스 및 도움 주는 사람들 많음
- 업그레이드는 스테이징/테스트환경에서 많이 하고 진행
 - 자동화 된 argocd 와 같은 tool 을 이용한 code 화 된 배포 프로세스를 사용하는 것이 좋음
- Object 사용시 csi 를 사용을 하는 경우가 많은데 불필요한 csi 의 태생이 filesystem 을 중점을 만들어 졌기에 불필요 하거나, 이슈가 많음
 - Ceph-cosi 가 정식적으로 릴리즈 된다면 많은 도움이 될 것 같다.